

Lezione 3 - 28/11/2022

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Many-body quantum systems

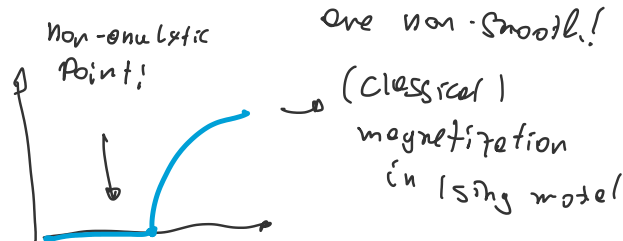
Why we want to study infinite systems of particles?

Some phenomena only happens in that setting.

example: phase transitions.

Thermal equilibrium state $w_\beta(x) = \frac{\text{Tr}(e^{-\beta H} x)}{Z_\beta}$

If $H(\mu)$ depends smoothly on a parameter μ
then w_β^μ is also smooth \rightarrow phase transitions
are non-smooth!



How can we study infinite systems?

Let Γ be a graph equipped with graph distance d

(more generally metric space)

examples $\Gamma = \mathbb{Z}$; $\Gamma = \mathbb{Z} \times \mathbb{Z}$; $\Gamma =$ hexagonal lattice

at each site $x \in \Gamma$, we associate a finite dim

quantum system $\mathcal{H}_x \cong \mathbb{C}^{d_x}$

d_x can depend on x but for simplicity I will

assume that $\sup_x d_x < +\infty$

Question: how to make sense of $\bigotimes_{x \in \Gamma} \mathcal{H}_x$?

Naive attempt at defining a tensor product:

$$a = (|a_x\rangle)_{x \in \Gamma} \quad |a_x\rangle \in \mathcal{H}_x$$

$$b = (|b_x\rangle)_{x \in \Gamma} \quad |b_x\rangle \in \mathcal{H}_x$$

$$\langle b, a \rangle \stackrel{?}{=} \prod_{x \in \Gamma} \langle b_x | a_x \rangle$$

It might not converge! e.g. $|b_x\rangle = (-1)^{\delta(x,0)} |a_x\rangle$

There are ways to solve this issue, but instead we will take a different route.

Local observables

Let $\Lambda \subset \Gamma$ finite. Define

$$\mathcal{H}_\Lambda = \bigotimes_{x \in \Lambda} \mathcal{H}_x \quad A_\Lambda = \mathcal{B}(\mathcal{H}_\Lambda) = \bigotimes_{x \in \Lambda} \mathcal{B}(\mathcal{H}_x)$$

If $\Lambda_1 \subseteq \Lambda_2$, then there is a natural inclusion

$$A_{\Lambda_1} \hookrightarrow A_{\Lambda_2}$$

$$X \longmapsto X \otimes \mathbb{1}_{\Lambda_2}$$

Now let $(\Lambda_n)_n$ an increasing ($\Lambda_{n+1} \supseteq \Lambda_n$)

and absorbing ($\forall x \in \Gamma \exists n$ such that $x \in \Lambda_n$)

sequence.

examples $\Lambda_n = [-n, n] \subseteq \mathbb{Z}$ or $\Lambda_n = [-n, n]^{k_2} \subseteq \mathbb{Z}^2$

Then $A_{loc} := \bigcup_n A_n$ local observables
 (operators with finite support)

and $A_p = \overline{A_{loc}}^{\|\cdot\|}$ operator norm (largest s.v.)

A_p is a unital C^* -algebra. Each A_Λ is a
 $*$ -subalgebra of A_p .

def: support

$M \in A_{loc}$ $SUPP M =$ smallest Λ s.t. $M \in A_\Lambda$

i.e. M acts as $\mathbb{1}$ outside $SUPP M$

Philosophy: Study A_p through the finite volumes Λ .

Idea: take Λ large but finite. Construct objects
 which either

- do not depend explicitly on $|\Lambda|$, or
- we can control their behavior as $|\Lambda| \rightarrow \infty$

Obtain a corresponding object on A_p .

Infinite volume dynamics: Local Hamiltonians

Local interaction: $X \subset \mathbb{C}^p$ finite $\mapsto h_X \in A_X$

Hermitian.

if $h_X = 0$ whenever $\text{diam}(X) > r_0$ } we will mostly
 focus on this
 case
 Then we say it has range r_0

exponential decay: $\|h_x\| \leq c \cdot e^{-\mu \text{diam}(x)}$

Usually exp. decay behaves similarly to finite range.

Polynomial decay on the other hand is quite different

example: $\Gamma = \mathbb{Z}$

Ising model $h_{ij} = \sigma_i^z \otimes \sigma_j^z$ if $|i-j|=1$ and 0 otherwise.

Cluster state $h_v = \sigma_{v-1}^z \otimes \sigma_v^x \otimes \sigma_{v+1}^z$

Local Hamiltonian. $\Lambda \subset \mathbb{C}^D$ finite

"open b.c."

$$H_\Lambda := \sum_{X \subseteq \Lambda} h_X$$

H_Λ is Hermitian and $d_t^\Lambda(x) = e^{itH_\Lambda} x e^{-itH_\Lambda}$

OBS $\|H_\Lambda\|$ can grow with $|\Lambda|$

$\Rightarrow \lim_{\Lambda \nearrow \Gamma} H_\Lambda = ???$ most probably not in \mathcal{A}_Γ

d_t^Λ is unital $*$ -homomorphism, $\|d_t^\Lambda\| = 1$

\Rightarrow Can we make sense of $\lim_{\Lambda \nearrow \Gamma} d_t^\Lambda$?

OBS $d_t^\Lambda : \mathcal{A}_\Lambda \rightarrow \mathcal{A}_\Lambda$, but we can extend it to \mathcal{A}_Γ .

if $X \otimes Y \in A_{loc}$ with $X \in A_1$ then

$$\mathcal{A}_t^1(X) = \mathcal{A}_t^1(X) \otimes Y$$

So by linearity $\mathcal{A}_t^1: A_{loc} \rightarrow A_{loc}$.

Let $(X_n)_n \in A_{loc}$ such that $X_n \rightarrow X \in A_p$ i.e.

$$\|X_n - X\| \rightarrow 0 \text{ as } n \rightarrow \infty$$

$$\begin{aligned} \|\mathcal{A}_t^1(X_n) - \mathcal{A}_t^1(X_m)\| &= \|\mathcal{A}_t^1\| \cdot \|X_n - X_m\| \\ &\rightarrow 0 \text{ as } n \rightarrow \infty \end{aligned}$$

\Rightarrow we can extend $\mathcal{A}_t^1: A_1 \rightarrow A_p$

def: **STRONG CONVERGENCE**

$\alpha_n: A \rightarrow A$ $\alpha_n \rightarrow \alpha$ strongly if

$$\|\alpha_n(M) - \alpha(M)\| \xrightarrow{n \rightarrow \infty} 0 \quad \forall M \in A$$

we want to find conditions which allow us to show that

$$\mathcal{A}_t^1 \rightarrow \mathcal{A}_t^p$$

this will require us to show that $\forall \epsilon, \forall X$.

$$\|\mathcal{A}_t^{\lambda_n}(X) - \mathcal{A}_t^{\lambda_m}(X)\| \rightarrow 0 \text{ as } n, m \rightarrow \infty$$

Important: we **FIX** X and t , **THEN** we let $\lambda \uparrow$!

Lieb-Robinson's bounds

Idea: speed of sound in a metal

1st order approx

$$\begin{aligned}
\hat{\alpha}_\epsilon(M_x) &= X + \epsilon [H_1, M_x] + o(\epsilon) \\
&= X + \epsilon \sum_{j \in \Lambda} [h_j, M_x] + o(\epsilon) \\
&= X + \epsilon \sum_{\substack{j \in \Lambda \\ y \cap X \neq \emptyset}} [h_j, M_x] + o(\epsilon)
\end{aligned}$$

If H is finite range,

then $\textcircled{1}$ does not depend on Λ but only on

$$\begin{aligned}
X(\pm 1) &= \{x \in \Lambda \mid \text{dist}(x, X) \leq 1\} \\
&= X + B_0(1)
\end{aligned}$$

2nd order

$$\begin{aligned}
\hat{\alpha}_\epsilon^2(M_x) &= X + \epsilon \sum_{\substack{j \in \Lambda \\ y \cap X \neq \emptyset}} [h_j, M_x] \\
&\quad + \frac{\epsilon^2}{2} \sum_{\substack{j_2 \in \Lambda \\ y_2 \cap X \neq \emptyset}} \sum_{\substack{j_1 \in \Lambda \\ y_1 \cap X \neq \emptyset}} [y_2, [y_1, X]] + o(\epsilon^2)
\end{aligned}$$

\Rightarrow We need to go to order ϵ^{ol} $d = \text{dis}(X, \Lambda^c)$
to see the dependence on Λ .

If we fix ϵ and X and let $\Lambda \nearrow \Gamma$, then $\hat{\alpha}_\epsilon^1(x)$ is Cauchy!

THM (Lieb-Robinson (1972))

Fix Γ and a local interaction $\{h_x\}_{x \in \Gamma}$. Then there exist positive constants C, μ, ν such that $\forall \epsilon > 0$

For any $\Lambda \subset \subset \Gamma$ finite

Let A supported on X , B supported on Y

$$X, Y \subseteq \Lambda \quad d = \text{dist}(X, Y) > 0$$

$$A(\epsilon) = \alpha_\epsilon^1(A)$$

$$\| [A(\epsilon), B] \| \leq c \cdot \|A\| \cdot \|B\| \cdot e^{-\mu(v\epsilon - d)}$$

v is called Lieb-Robinson or Group Velocity

Obs 1: R.h.s. is small if $d \gg v\epsilon$

$\Rightarrow v$ is a "velocity" $\sim \frac{\text{distance}}{\text{time}}$.

Obs 2: If A is such that

$$\| [A, B] \| \leq \epsilon \|A\| \cdot \|B\|$$

for all B supported on Y

then $\exists A'$ supported on Y^c s.t.

$$\|A - A' \otimes \mathbb{1}_Y\| \leq \epsilon \|A\|$$

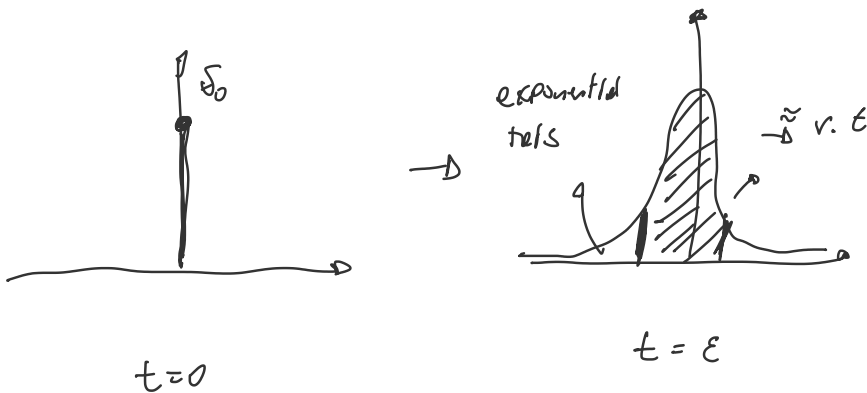
Proof: exercise

\Rightarrow LR bounds imply that, if $t \ll \frac{d}{v}$, then

$\alpha_\epsilon^1(A)$ has support "almost" in $X(d)$,

up to exponential tails.

Similar to what happens in heat equation



Can let $\Lambda \subset \mathbb{R}^d$ and $X \subseteq \Lambda$.

Let $d = \text{dist}(x, \mathbb{R}^c)$ and A supported on X

Consider $A(t) = \mathcal{A}_t^1(A)$ for $0 \leq t \leq t_{\max} \ll \frac{d}{v}$
 in the sense that $C e^{M(v t_{\max} - d)} \leq \epsilon$
 For some fixed $\epsilon > 0$.

Then $A(t)$ is well approximated by $\tilde{A}(t)$

$$A(t) \approx \mathcal{A}_t^{X(c \cdot v \cdot t)}(A)$$

$$\|A(t) - \tilde{A}(t)\| \leq \epsilon \|k\| \quad \forall 0 \leq t \leq t_{\max}$$

And by construction $\text{supp } \tilde{A}(t) = X(c \cdot v \cdot t)$

